## Incremental Shaft Encoders Type RI 76 TD

### with Hollow Shaft



NUMBER OF PULSES

TECHNICAL DATA mechanical

■ Through shaft with up to diameter 42 mm

Short overall length with an outside diameter of only 76 mm

Easy installation by means of clamping ring

Operating temperature up to 100 °C

Application e.g.:

- motors

- printing machines

- lifts

50 / 100 /250 / 300 / 500 / 600 / 900 / 1,000 / 1,024 / 1500 / 2,048 / 2,500 / 3,072 / 4096 / 5,000 / 9,000 / 10,000

Other numbers of pulses available on request

C1				
Shaft fixation		clamping ring, front or rear		
Coupling	stator coupling (spring plate)			
Shaft diameter	1542 mm (Availab	ole: 15, 16, 18, 20, 24, 25, 27, 28, 30,		
	32, 38, 40, 42 mm a	also 5/8", 15/8", 3/4")		
Minimum length of mounting shaft				
Front clamping ring	32 mm with Ø 1530, 35 mm with Ø $>$ 3042			
Rear clamping ring	corresponding to total length of encoder			
Max. parallel shaft misalignment				
With flexible stator coupling A (fle	xible)	±2.0 mm axial, ±0.15 mm radial		
With 1 x flexible stator coupling N	(torsionally rigid)	±0.5 mm axial, ±0.3 mm radial		
With 2 x flexible stator coupling N	(torsionally rigid)	±0.3 mm axial, ±0.2 mm radial		
Absolute maximum speed	at 70° C and IP 64:	3,600 RPM for Ø 1525		
	at 70° C and IP 64:	1,800 RPM for Ø > 2542		
	at 70°C and IP 40:	6,000 RPM for Ø 1542		
	at 100° C always:	1,800 RPM for Ø 1542		
Torque	310 Ncm (depending on version)			
Moment of inertia	140420 gcm <sup>2</sup> (depending on version)			
Protection class (EN 60529	Housing IP 50, bearings IP 40			
Option:	Housing IP 65, bearings IP 64			
Operating temperature	-25+100 °C			
Storage temperature	-25+100 °C			
Vibration proof (IEC 68-2-6)	$10 g = 100 \text{ m/s}^2 (10)$	) 2,000 Hz)		
Shock resistance (IEC 68-2-27)	100 g = 1,000 m/s <sup>2</sup>	(6 ms)		
Type of connection	1.5 m cable 1) radia	I		
Housing	aluminium			
Weight	320 - 580 g (depen	ding on version)		
1) 0:1				

<sup>1)</sup> Other cable length on request

General design as per DIN EN 61010, protection class III, contamination level 2, overvoltage class II with RS 422 (R, T):  $5 \text{VDC} \pm 10 \%$ with push-pull (K, I):  $10 \dots 30 \text{VDC}^{-1}$ Supply voltage 10 ... 30 VDC 1) (SELV) 60 mA (5 VDC), 60 mA (10 VDC), 35 mA (24 VDC) Power consumption Standard-RS 422 (R): A, B, N,  $\overline{A}$ ,  $\overline{B}$ ,  $\overline{N}$ ,  $\overline{Alarm}$ A, B, N,  $\overline{A}$ ,  $\overline{B}$ ,  $\overline{N}$ , Sense RS 422 (T): Output versions 2) push-pull (K): A, B, N, Alarm push-pull complementary (I): A, B, N, A, B, N, Alarm

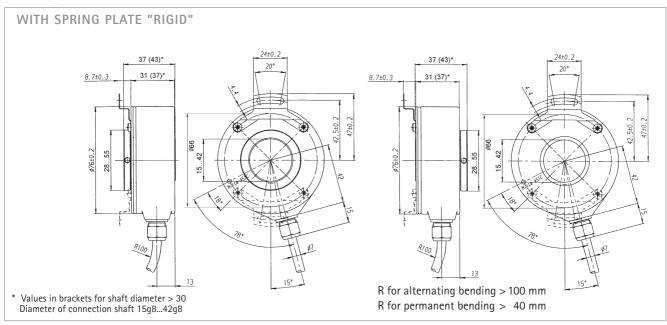
TECHNICAL DATA electrical

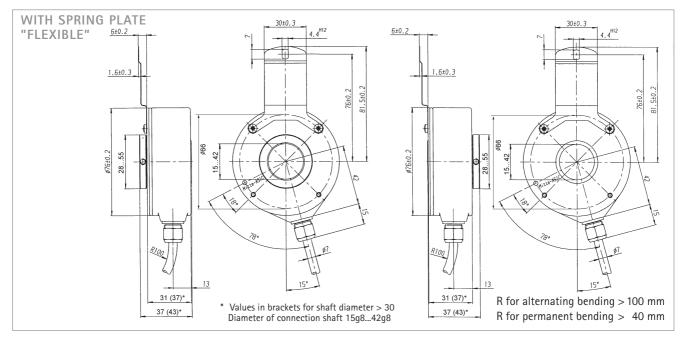
<sup>&</sup>lt;sup>1)</sup> Pole protection with supply voltage 10 ... 30 VDC

<sup>&</sup>lt;sup>2)</sup> Output description and technical data see section "output".

## Incremental Shaft Encoders Type RI 76 TD with Hollow Shaft

#### DIMENSIONED DRAWING





#### **SHAFT CONNECTION**

Shaft fixing is done through a clamping ring either on the flange or cap side. As a rule, flange side clamping is better for smaller motors as the available shaft stub is correspondingly shorter. On the other hand, cap side clamping is easier when there is sufficient shaft length available.

#### MOUNTING NECESSITIES

In order to compensate for axial and radial shaft eccentricity as well as any angle offset, the encoder flange may not be rigidly mounted. Please mount the flange with a flexible stator coupling (e.g. spring plate) as torque support. There are two flexible mounting plates:

- A flexible spring plate (A) for higher levels of play and lower requirements for accuracy.
- A rigid spring plate (N) for reduced play and rigid connection with reduced swing angle. This is suitable in the case of higher accuracy and dynamics requirements.

# Incremental Shaft Encoders Type RI 76 TD with Hollow Shaft

## CONNECTION DIAGRAM CABLE TPE

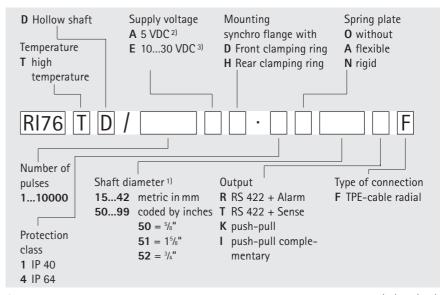
	Output circuit			
Colour (TPE)	RS 422	RS 422	push-pull (K)	push-pull
	+ Sense (T)	+ Alarm (R)		complementary (I)
brown	Channel A	Channel A	Channel A	Channel A
green	Channel A	Channel A		Channel A
grey	Channel B	Channel B	Channel B	Channel B
pink	Channel B	Channel B		Channel $\overline{B}$
red	Channel N	Channel N	Channel N	Channel N
black	Channel $\overline{N}$	Channel $\overline{N}$		Channel $\overline{N}$
violet (white) 2)	Sense GND	Alarm	Alarm	Alarm
blue	Sense V <sub>cc</sub>	Sense V <sub>cc</sub>		Sense V <sub>cc</sub>
brown/green	5 VDC=	5/10 30 VDC=	10 30 VDC=	10 30 VDC=
white/green	GND	GND	GND	GND
Screen 1)	Screen 1)	Screen 1)	Screen 1)	Screen 1)

<sup>1)</sup> connected to housing

#### **ACCESSORIES**

Spring plate, flexible	Ordering code 1 533 079
Spring plate, rigid	Ordering code 1 533 078

#### ORDERING DATA



<sup>1)</sup>Available with front clamping ring and IP 40: 15, **20**, **24**, 25, 27, 28, 30, 38, 40, 42, 50 (%"), 51 (1%") Available with front clamping ring and IP 64: **15**, 16, 18, **20**, 24, **25**, 27, 28, 30, 32, **38**, **40**, **42**,

50 (5/4"), 51 (15/4"), 52 (3/4")

Available with rear clamping ring and IP 40: 25, 28, 30, 32, 38, 40, 42 Available with rear clamping ring and IP 64: 20, **25,** 30, 32, 38, 40, **42** 

Bold printed: preferred versions Others: please request delivery time

2) only with output R, T, K

 $^{3)}$  only with output R, K, I

<sup>2)</sup> white for RS 422 + Sense (T)